## Overview of Topics

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## List of topics

- Random hashing
- Probabilistic streaming and sketching algorithms
- Matrix decompositions (including NMF and probabilistic)
- Random graph theory / percolation theory
- Wavelet bases
- Complexity and entropy
- Nonlinear dimensionality reduction
- Computational topology


## Possibly out-of-scope topics (because ML)

These are all super fun topics, but also covered in many other classes. Take e.g. Prof. Papyan's MAT1510 instead:
https://sites.google.com/view/mat1510

- Clustering
- Linear classifiers
- Kernel methods
- Deep learning
- Graphical models


## Machine Learning

- Intuition: try to learn the underlying probability distribution generating the data we care about.
- An algorithm builds a mathematical model based on training data, which it uses to make predictions or decisions on new data.
- We say that model parameters are "learned" from the data.
- We focus here on the supervised classification task, though many of the other topics in data science are sometimes "considered" ML.


## ML: linear classifier

- Given an input vector $\boldsymbol{x}$, the output $y=f(\boldsymbol{w} \cdot \boldsymbol{x})$, where the weights $\boldsymbol{w}$ are learned from the data should match label $l$.
- Simple example: $f(a)=1$ if $a>$ $t$, for some threshold $t$, and 0 otherwise.

-Dividing hyperplane, separating classes 0 and 1.


## ML: linear classifiers

- Perceptron algorithm
-Technical modification, $\widehat{\boldsymbol{x}}=(\boldsymbol{x}, 1), \widehat{\boldsymbol{w}}=(\boldsymbol{w},-t)$, making separating hyperplanes go through the origin.
-Initialize with $\boldsymbol{w} \leftarrow 0$.
-While there exists $\boldsymbol{x}_{\boldsymbol{i}}$ with $\boldsymbol{x}_{\boldsymbol{i}} l_{i} \cdot \boldsymbol{w} \leq 0$, update $\boldsymbol{w} \leftarrow \boldsymbol{w}+\boldsymbol{x}_{\boldsymbol{i}} l_{i}$, where $l_{i}=\{-1,1\}$ is class label.
- SVM (Support Vector Machine)
-Tries to find the maximum-margin hyperplane, not just any hyperplane (like perceptron).


## ML: kernel trick

- Data may not be linearly separable
- But we can often map the data to another space where it is linearly separable.
- E.g. $\varphi\left(\left(x_{1}, x_{2}\right)\right)=\left(x_{1}, x_{2}, x_{1}^{2}+x_{2}^{2}\right)$
- Kernel: $K(\boldsymbol{x}, \boldsymbol{y})=\varphi(\boldsymbol{x}) \cdot \varphi(\boldsymbol{y})=\boldsymbol{x} \cdot \boldsymbol{y}+|\boldsymbol{x}|^{2}|\boldsymbol{y}|^{2}$
- Careful choice of map allows using kernel function instead of explicit mapping.



## ML: deep learning

- Chaining together a bunch of simple nonlinear classifiers empirically improves classification.
- Each node represents a linear combination of parent node values, modified by a nonlinearity (often a ReLU).
- Empirically, using a deep network allows us to use a much simpler nonlinearity than more complicated kernel functions.



## ML: back-propagation

- The network can be thought of as a function

$$
g(x)=f^{L}\left(W^{L} f^{L-1}\left(W^{L-1} \cdots f^{1}\left(W^{1} x\right) \cdots\right)\right)
$$

where, $f^{l}$ is the nonlinearity, and $W^{l}$ is a weights matrix at layer at layer $l$.

- We also have a loss/cost function $C\left(y_{i}, g\left(x_{i}\right)\right)$, where $y_{i}$ is the true label of a data point $x_{i}$.
- We want to use gradient descent to optimize the weights based on the training data.
- Each individual component of the gradient $\partial C / \partial w_{j k}^{l}$ can be computed via the chain rule.
- The back-propagation algorithm avoids duplicate calculations by computing the gradient of each layer from back to front. (i.e. starting from the output layer)


## Clustering

- Grouping together data points into "meaningful" groups.
- Also known variously as partitioning, community detection, finding spin glass states, etc.
- Two major versions
-High-dimensional space (not just vector spaces)
-On a graph
- Hard and soft (depending on group assignment)

https://en.wikipedia.org/wiki/K-means clustering



## K-means

- Given a set of observations $\left(x_{1}, \ldots, x_{n}\right), x_{i} \in \mathbb{R}^{d}$, find a partition $\boldsymbol{S}=$ $\left\{S_{1}, \ldots, S_{k}\right\}$ that minimizes squared distances to cluster centers.
- Naïve k-means algorithm
-Initialize means (e.g. with random choice)
-Iterate until convergence:
- Assign each observation to nearest cluster center
- Calculate new cluster means based on assignment.
- Converges if using Euclidean distance


## Hierarchical clustering

- E.g. on a graph, repeatedly cut the graph in half to minimize the cut weight.
- Alternately, iteratively link together pairs of points that are closest together.

https://en.wikipedia.org/wiki/Hierarchical clustering


## Scoring functions

- E.g. Girvan-Newman modularity.
-The fraction of edges within clusters minus the expected fraction if edges were distributed at random (under several different random graph models).
- Related to Hamiltonian of spin glass in physics. (i.e. energy of a system where adjacent nodes want the same spin).
- Cluster scoring function independent of number of clusters. Often paired with a hierarchical clustering algorithm to allow choosing the correct level.


## (Gaussian) mixture models

- Recall we covered a simple Gaussian mixture model where we assumed our dataset was generated by a combination of different radially symmetric Gaussians.
- In general, let $p(\theta)=\sum_{i=1}^{K} \phi_{i} \mathcal{N}\left(\mu_{i}, \Sigma_{i}\right)$, where $\phi_{i}$ is a weight associated with each multivariate Gaussian distribution $\mathcal{N}\left(\mu_{i}, \Sigma_{i}\right)$.
- How can we estimate $p(\theta)$ from a bunch of samples drawn from it?


## Expectation-maximization iterative algorithm

- One commonly used iterative technique to fit parameters $\theta$ and missing latent variables $Z$ is the EM-algorithm.
- Algorithm:
-Initialize parameters $\theta$ to random values
-Compute the probability of each possible value of $Z$, given $\theta$ (E-step).
-Then, use the just-computed values of $Z$ to compute a better estimate for the parameters $\theta$ ( M -step)
-Iterate the last two steps until convergence.


## Hidden Markov models (HMM)

- Let $X_{n}$ and $Y_{n}$ be discrete-time stochastic processes and $n \geq 1$. The pair $\left(X_{n}, Y_{n}\right)$ is a Hidden Markov Model if $X_{n}$ is a Markov process and not directed observable and $P\left(Y_{n} \in A \mid X_{1}=x_{1}, \ldots, X_{n}=x_{n}\right)=$ $P\left(Y_{n} \in A \mid X_{n}=x_{n}\right)$.
- Generalization of a mixture model where the hidden (latent) variables controlling the mixture component are related through a Markov chain instead of independent.
- System being modelled is assumed to be a Markov process with unobservable (hidden) states.
- Can be learned using a variation of the EM algorithm.


## Hidden Markov Models

- Inference tasks:
-given parameters of a model, compute probability of a particular output sequence.
-Figure out the distribution over hidden states of the last latent variable at the end of the sequence.


https://en.wikipedia.org/wiki/Hidden Markov model


## Graphical models

- "Graphical" in the sense of "graph theory"
- A graphical model is a compact representation of a probability distribution over $n$ variables $x_{1}, \ldots, x_{n}$.
- When using a directed acyclic graph, is known as a Bayesian or belief network.
- When using an undirected graph, is known as a Markov random field


## Bayesian or Belief networks

$$
p\left(x_{1}, \ldots, x_{n}\right)=\prod_{i=1}^{n} p\left(x_{i} \mid \text { parents of } x_{i}\right)
$$

- Each directed edge from $y$ to $x$ represents a conditional probability $p(y \mid x)$.
- A variable without any in-edges has an unconditional probability distribution.
- We observe only certain variables, known as "evidence".
- E.g. A doctor observes an ill patient's symptoms


Blum, Hopcroft, Kannan, 2020

- What disease does the patient have?
- What is the probability of a specific disease?


## Markov random field

- Given an undirected graph $G=(V, E)$, a set of random variables $X=$ $\left(X_{v}\right)_{v \in V}$ indexed by $V$ form a Markov random field with respect to $G$ if every variable is conditionally independent of all other variables given its neighbors.



## Markov random field examples

- Application: Ising model of spin glasses / community detection.
-Each particle $x_{1}, \ldots, x_{n}$ can have a spin $\pm 1$, and the energy of the system is $\exp \left(c \sum_{i \sim j}\left|x_{i}-x_{j}\right|\right)$.
-Minimizing the energy, subject to specified constraints, is a Markov random field.
- Application: Image reconstruction
-Each pixel is a graph vertex, and we may wish nearby pixels to be similar, with some penalty.


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- Wavelet bases
- Complexity and entropy
- Nonlinear dimensionality reduction
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## Random hashing

- Real data has all kinds of often unknown probability distributions
- Two approaches to handling large data:
- Try to understand the distributions it comes from (ML)
- Force it into a particular distribution that we can reason about (hashing and projections)
- An idealized oracle hash function $f: U \rightarrow[0,1)$ maps each item in $U$ to a uniform random number between 0 and 1 .
- Such an oracle would however be expensive to store.
- Can we approximate an idealized hash function with less randomness?


## Sketching algorithms

- Sub-linear space algorithms
- Family of algorithms for representing big data as small probabilistic data structures called "sketches"
- Fast accurate estimates of cardinality, quantiles, frequency distributions, set membership, majority element, etc.
- Widely used: routers, databases, search, etc.
- Also used in software for (meta)genome distance approximation, including Mash and Dashing.


## Count Distinct Problem

- How many distinct items exist in a list? [Flajolet, Martin, Ziv Bar-Yossef]

- Expected minimum is about $\frac{1}{n+1}$, so we need $O(\log (n))$ bits of storage.


## (Hyper)LogLog counting [Flajolet, et al]

- Only need to store the order of magnitude to get a good estimate, so can compress hashed values.

- With some correction terms, get errors that are $O\left(\frac{1}{\sqrt{k}}\right)$, where $k$ is number of buckets / iterations.
- But need only $O(\log \log (n))$ space.


## HyperLogLog set operations

- Union cardinality
- Cardinality of the union of sets is lossless with HLL
- Determine the largest value for each bucket (iteration)
- Estimate cardinality using the new sketch

| 3 | 6 | 4 | 1 | 5 | 2 | 2 | 4 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 2 | 3 | 3 | 4 | 2 | 3 | 1 | 6 |
| 5 | 3 | 1 | 0 | 7 | 4 | 3 | 3 |$\quad-$| 5 | 6 | 4 | 4 | 7 | 4 | 3 | 6 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

- Intersection cardinality
- Use inclusion-exclusion principle: $|A \cap B|=|A|+|B|-|A \cup B|$
- Only accurate if the union and intersection cardinalities are comparable.
- Complexity grows exponentially with number of sets



## Jaccard index [Jaccard, 1902]

- Measures the similarity between two sets by

$$
J(A, B)=\frac{|A \cap B|}{|A \cup B|^{\circ}} .
$$



## MinHash [Broder, 1997]



## MinHash [Broder, 1997]



$$
\operatorname{Prob}(\min (A)=\min (B))=\frac{|A \cap B|}{|A \cup B|}=J(A, B)
$$

## MinHash: a worked example

|  | $\|A\|=5 \mathrm{M}$ | $\|A \cap B\|$ | $\|B\|=10 \mathrm{M}$ |
| :---: | :---: | :---: | :---: |
|  | 0.1548 |  | 0.0358 |
|  | 0.1422 |  | 0.0657 |
| 5 | 0.0559 | = | 0.0559 |
| - | 0.1287 |  | 0.0400 |
| n | 0.0811 | = | 0.0811 |
| $\stackrel{0}{0}$ | 0.1208 |  | 0.2649 |
| $\pm$ | 0.1153 |  | 0.0120 |
| $J(A, B) \approx \frac{2}{7}$ |  |  |  |


| $\|A\|=5 \mathrm{M}$ | $\|\boldsymbol{A} \cup \boldsymbol{B}\|$ | $\|\boldsymbol{B}\|=10 \mathrm{M}$ |
| :---: | :---: | :---: |
| 0.1548 | 0.0358 | 0.0358 |
| 0.1422 | 0.0657 | 0.0657 |
| 0.0559 | 0.0559 | 0.0559 |
| 0.1287 | 0.0400 | 0.0400 |
| 0.0811 | 0.0811 | 0.0811 |
| 0.1208 | 0.1208 | 0.2649 |
| 0.1153 | 0.0120 | 0.0120 |
| Can merge <br> sketches |  |  |

## Turnstile streams

- Begin with an $n$ length vector $x$ initialized to 0 .
- Stream in a set of updates in the form $\{i, v\}$, where $i \in\{1, \ldots, n\}$ and $v$. For each update set $x_{i} \leftarrow x_{i}+v$.
- After streaming, return approximately $f(x)$ for some $f$. Ideally, for some $f$, do not need to store all of $x$. Examples:
-p-norm
-Largest entries (heavy hitters)


## AMS Sketch: $F_{2}=|x|_{2}^{2}$

- Let $\Pi=\frac{1}{\sqrt{m}}\left[\begin{array}{ccc} \pm 1 & \cdots & \pm 1 \\ \vdots & \ddots & \vdots \\ \pm 1 & \cdots & \pm 1\end{array}\right] \in \mathbb{R}^{m \times n}$, where each row is chosen pseudorandomly by a 4-wise independent hash function, so the matrix can be represented in $O(m \log n)$ bits.
- Store $y \leftarrow y+v \Pi_{\mathrm{i}}$ where $\Pi_{i}$ is the $i$ th column.
- Then $|y|_{2}^{2}$ is an estimator of $|x|_{2}^{2}$.
- Requires $O\left(\frac{1}{\epsilon^{2}} \log \frac{1}{\delta}\right)$ space to estimate with $1-\delta$ probability to within $\epsilon$ relative error.


## Nonnegative matrix factorization

- Consider the Topic Modelling problem
-Suppose there exist $r$ topics and and $n$ documents, which are a mixture of the topics, determining the probability distribution of words (or phrases) in the document.
-We want to determine both the topics that exist, as well as what topics the documents are mixtures of.



## NMF (continued)

- Cannot use SVD for topic modelling because some of the low-rank "topics" will have negative numbers of particular words.
- Hence, we need non-negative matrix factorization
- i.e. decompose a matrix $A=B C$, where all entries are non-negative, and the columns of $B$ and $C$ sum to 1 .
- Algorithms for NMF are much more complicated than SVD, but can be done in $O(p o l y(r))$ time, where $r$ is the rank of the matrix.


## Random graphs

- Networks of connected nodes show up often
-Electrical grids
-Social networks
-Protein interaction networks
- Real-world networks can be analyzed using things like graph partitioning, or random walks on a particular network. However, we may also be interested in modelling the generation of the network itself.


## Random graphs - Erdos-Renyi

- $G(n, p)$ model, where $n$ is the number of vertices, and $p$ is the edge probability.
- Degree is tightly concentrated around $n p$, and in fact binomial with mean $n p$.
- Has sudden phase transition in number of connected components at expected degree $d=1$.
- Degree of separation also has a sharp threshold.
- Has related applications in designing CNF solvers for SAT problems.


## Percolation Theory and random graphs

- Suppose you have an alloy of an electrical conductor and an insulator, with the atoms intermingled in the form of a cable.
- So long as you have a path from one end of the cable to the other composed entirely of conductive atoms, the cable itself is conductive.
- How much insulator can you put into the cable while it remains conductive?



## Random graphs - Preferential attachment

- Real social networks however do not look like Erdos-Renyi graphs.
- One easy way to see this is to look at the degree distribution.
- Preferential attachment (rich get richer) is one common model that promotes both small-world graphs and the long-tail behavior of real social networks.



## Random graphs - Conf-model

- But what about networks whose properties we have trouble approximating using a simple model?
- Can we still generate a random network with e.g. the same degree distribution as a real one?
- One way to do this is the configuration random model. Start with an existing network (or set of degree distributions), cut each edge in half, and then randomly reattach edge-halves.
- Used in the null model for Girvan-Newman modularity clustering score.


## Wavelets: background (FT)

- Recall the Fourier transform, which gives a basis in terms of sines and cosines for the space of functions.
-Each of the basis functions contains information localized in frequency, but not in space/time.
-Hard to represent discontinuities.



## Wavelets: motivation

- Want an easy-to-compute-with orthogonal basis set of functions that have finite support.
- Finite support makes it easier to represent functions that have discontinuities.
- The basis should be composed of simple pieces, like sines and cosines for the Fourier transform.


## Wavelets: dilations

- Dilations are mappings that scale all distances by the same factor.
- A dilation equation is a function defined in terms of linear, scaled, shifted versions of itself.

$$
f(x)=f(2 x)+f(2 x-1)
$$




$$
\begin{aligned}
& f(x) \\
& =\frac{1}{2} f(2 x)+f(2 x-1)+\frac{1}{2} f(2 x-2)
\end{aligned}
$$



## Wavelets: construction

- Start from a dilation equation, and a solution $\phi(x)$
- We define a 2 D set of scaling functions

$$
\phi_{j k}(x)=\phi\left(2^{j} x-k\right)
$$

- For a fixed value of $j$, the $\phi_{j k}$ span a space $V_{j}$.
- If $\phi(x)$ satisfies a dilation equation of the form

$$
\phi(x)=\sum_{k=0}^{d-1} c_{k} \phi(2 x-k)
$$

Then each $\phi_{j k}$ is a linear combination of $\phi_{j+1, k}$ 's.

- Thus $V_{0} \subseteq V_{1} \subseteq V_{2} \subseteq \cdots$
- We can then approximate a function by choosing $V_{k}$


## Wavelets: Haar wavelet

$$
\begin{aligned}
& f(x)=f(2 x)+f(2 x-1) \\
& \phi(x)=1 \text { if } x \in[0,1] \\
& \phi_{j k}(x)=\phi\left(2^{j} x-k\right)
\end{aligned}
$$

## Wavelets: Haar wavelet

- But the set of functions given above is not orthogonal, so reduce set to a linearly ind. set.
- The Haar wavelet is defined by the following basic functions, but with certain members that are linearly dependent removed.

The Haar Wavelet

$$
\phi(x)= \begin{cases}1 & 0 \leq x<1 \\ 0 & \text { otherwise }\end{cases}
$$


$\psi(x)=\left\{\begin{array}{cc}1 & 0 \leq x<\frac{1}{2} \\ -1 & \frac{1}{2} \leq x<1 \\ 0 & \text { otherwise }\end{array}\right.$


## Wavelets: applications

- Applications
-Data compression
-Signal processing
-Power-line communication protocols
- Issues
-Often need to design a wavelet system specific to the problem. i.e. Haar is often not the most natural.
-Smoothness of the basis functions can sometimes be desirable.


## Nonlinear dimensionality reduction

- SVD and related methods like PCA allows you to reduce the dimensionality of a dataset down linearly.
- What if your dataset is actually nonlinear?
- What techniques do we have to reduce dimensionality while preserving structure?
-E.g. t-SNE and UMAP, among others.

https://en.wikipedia.org/wiki/Nonlinear_dimension ality_reduction\#/media/File:Lle_hlle_swissroll.png


## Persistent homology

- Method for computing topological features of a space at different spatial resolutions.
- Represent a data cloud as a simplicial complex.
- A distance function specifying links between neighboring points corresponds to a filtration on the simplicial complex.
- We can then ask questions about the simplicial homology at a particular resolution.
- Persistent homologies are the long-lived features.


## Persistent homology: math

- Let $S$ be a simplicial complex.
- A simplicial k-chain: $\sum_{i=1}^{N} c_{i} \sigma_{i}$ where $c_{i} \in \mathbb{Z}$ and $\sigma_{i}$ is an oriented $k$-simplex (and $-\sigma_{i}$ is the opposite oriented ${ }^{L}$ simplex).
- The free abelian group of $k$-chains on $S$ is written $C_{k}$, and has basis in 1-1 correspondence with $k$-simplices.
- The boundary operator $d_{k}: C_{k} \rightarrow C_{k-1}$ is a homomorphism given by $d_{k}(\sigma)=$ $\sum_{i=1}^{k}(-1)^{i}\left(\sigma_{\hat{\imath}}\right)$, where $\sigma_{\hat{\imath}}$ is the $i$ th face of $\sigma$, obtained by deleting its $i$ th vertex.
- Let $Z_{k}=\operatorname{ker} \delta_{k}$, the subgroup of cycles.
- Let $B_{k}=\operatorname{im} \delta_{k+1}$, the subgroup of boundaries.
- The $k$ th homology group is defined as the quotient abelian group $H_{k}(S)=Z_{k} / B_{k}$, which is nonzero when there are $k$-cycles on $S$ which are not boundaries. (i.e. $k$-dim holes in the complex)
- The $k$ th Betti number of $S$ is $\beta_{k}=\operatorname{rank}\left(H_{k}(S)\right)$.


## Persistent homology: visualization

- Example: connected components ( $\beta_{0}$ ), loops ( $\beta_{1}$ ), higher-dimensional holes ( $\beta_{i}$ ).



## Persistent homology: connected components



## Persistent homology: loops



## Persistent homology: signals

Signal
Threshold ( $\tau$ ): 0.90


## Persistent homology: applications

- Compression of signals and images via storing only persistence diagram (keeping track of critical points in the signal), or maybe even only a subset of the persistence values of highest magnitude.
- Using the persistence diagram as an additional global feature of a dataset, e.g. as input into a machine learning pipeline.
-i.e. are the persistent features of a data cloud of gut microbiome compositions correlated with the healthiness of the individual.

