

# Approximating functions

## Lecture 11c: 2021-08-04

MAT A35 – Summer 2021 – UTSC

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# Approximating $\sin x$

- Recall the Taylor series  $\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \frac{x^9}{9!} - \dots$
- Can you approximate  $\sin 0.5$  by hand?

$$\sin 0.5 = 0.5 - \frac{0.5^3}{3!} + \frac{0.5^5}{5!} - \frac{0.5^7}{7!} + \dots$$

$$= 0.5 - \frac{0.125}{6} + \frac{0.03125}{120} - \dots$$

$$\approx 0.5 - 0.020833\dots$$

$$\approx \underline{0.47916\dots}$$

$$\sin 0.5 = \underline{0.4794255}$$

- We can often approximate a function by cutting off its Taylor series after some number of terms.

# Try it out

- What is  $e^{0.5}$ , approximated using the first 3 terms in its Maclaurin series?

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

$$2! = 2 \cdot 1 = 2$$

$$e^{0.5} \approx 1 + 0.5 + \frac{0.5^2}{2} = 1.5 + \frac{1}{8} = 1.5 + 0.125 = 1.625$$

$$e^{0.5} = 1.6487$$

- A: 1
- B: 1.5
- C: 1.5625
- D: 1.6487
- E: None of the above

# Constant approximation of a function

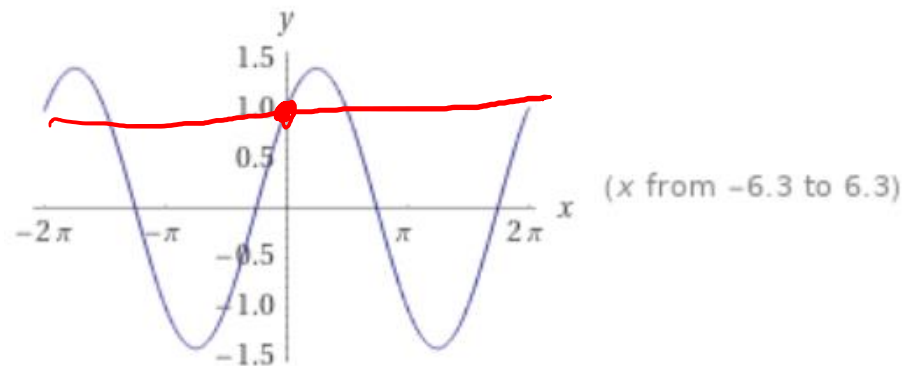
$$0! = 1 \quad 1! = 1 \quad 2! = 2 \cdot 1 \quad 5! = 5 \cdot 4 \cdot 3 \cdot 2 \cdot 1$$

- If we keep just the first term of a Taylor series, we get a constant approximation.

Ex.  $f(x) = \sin x + \cos x$

Taylor series  $\underline{f(0)} + f'(0)x + \frac{f''(0)}{2!}x^2 + \dots$

$\sin x + \cos x \rightarrow f(0) = 1$  around 0.



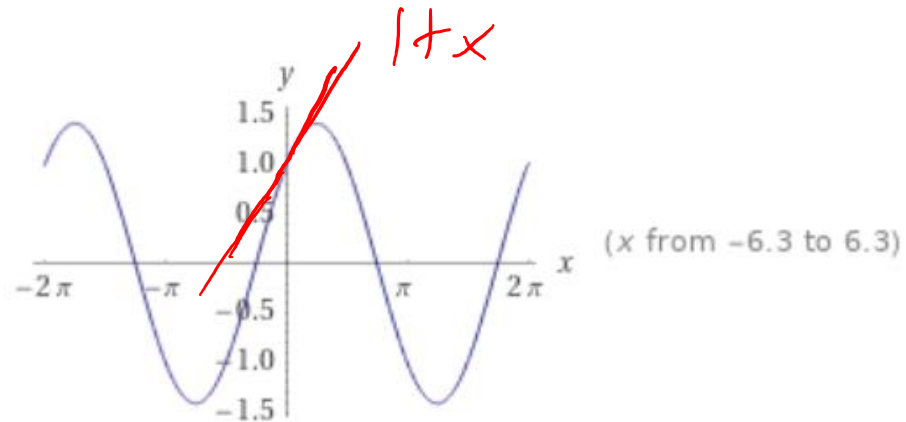
# Linear approximation of a function

- If we keep just the first two terms of a Taylor series, we get a linear approximation.

Ex.

$$f(x) = \sin x + \cos x \quad f(0) = 1$$
$$f'(x) = \cos x - \sin x \quad f'(0) = 1$$

Taylor series  $f(x) \approx 1 + x$



# Quadratic approximation of a function

- If we keep just the first three terms of a Taylor series, we get a quadratic approximation.

Ex.

$$f(x) = \sin x + \cos x$$

$$f'(x) = \cos x - \sin x$$

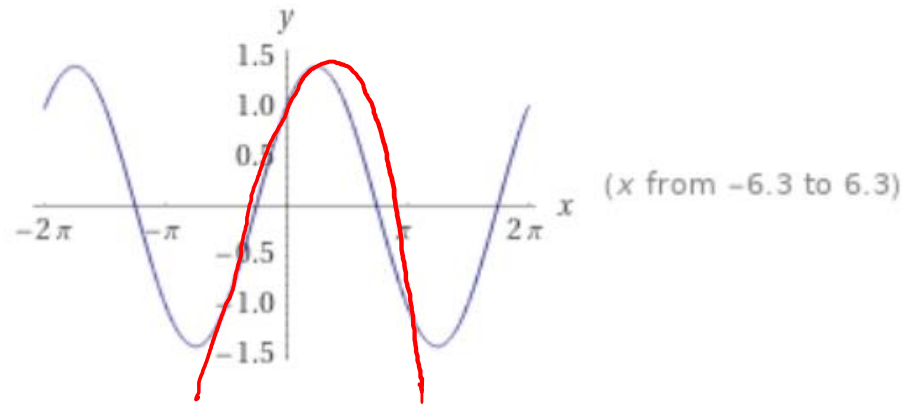
$$f''(x) = -\sin x - \cos x$$

$$f(0) = 1$$

$$f'(0) = 1$$

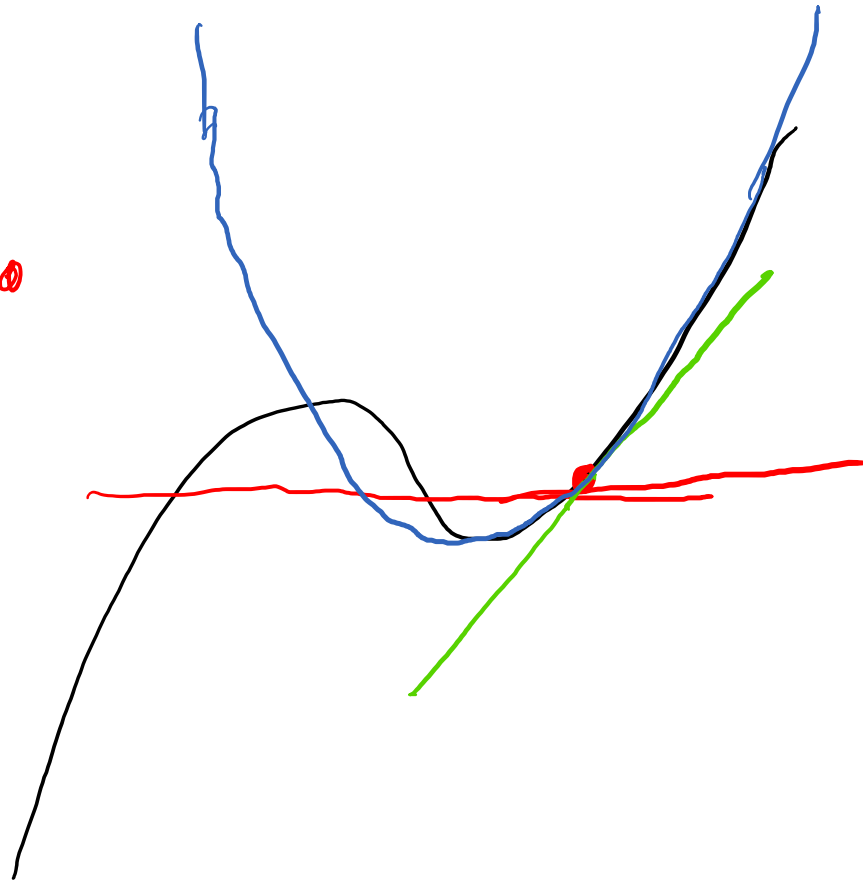
$$f''(0) = -1$$

$$f(x) \approx 1 + x - \frac{x^2}{2}$$



# Qualitative analysis using approximation

- Often, the qualitative facts we are interested in can be captured by linear or quadratic approximation.
- Constant approximation: roughly where is the function? ①
- Linear approximation: is the function increasing or decreasing? ②
- Quadratic approximation: is the function concave up or down? ③



# Multivariable functions

- A function  $f(x)$  has a linear approximation at  $a$  of

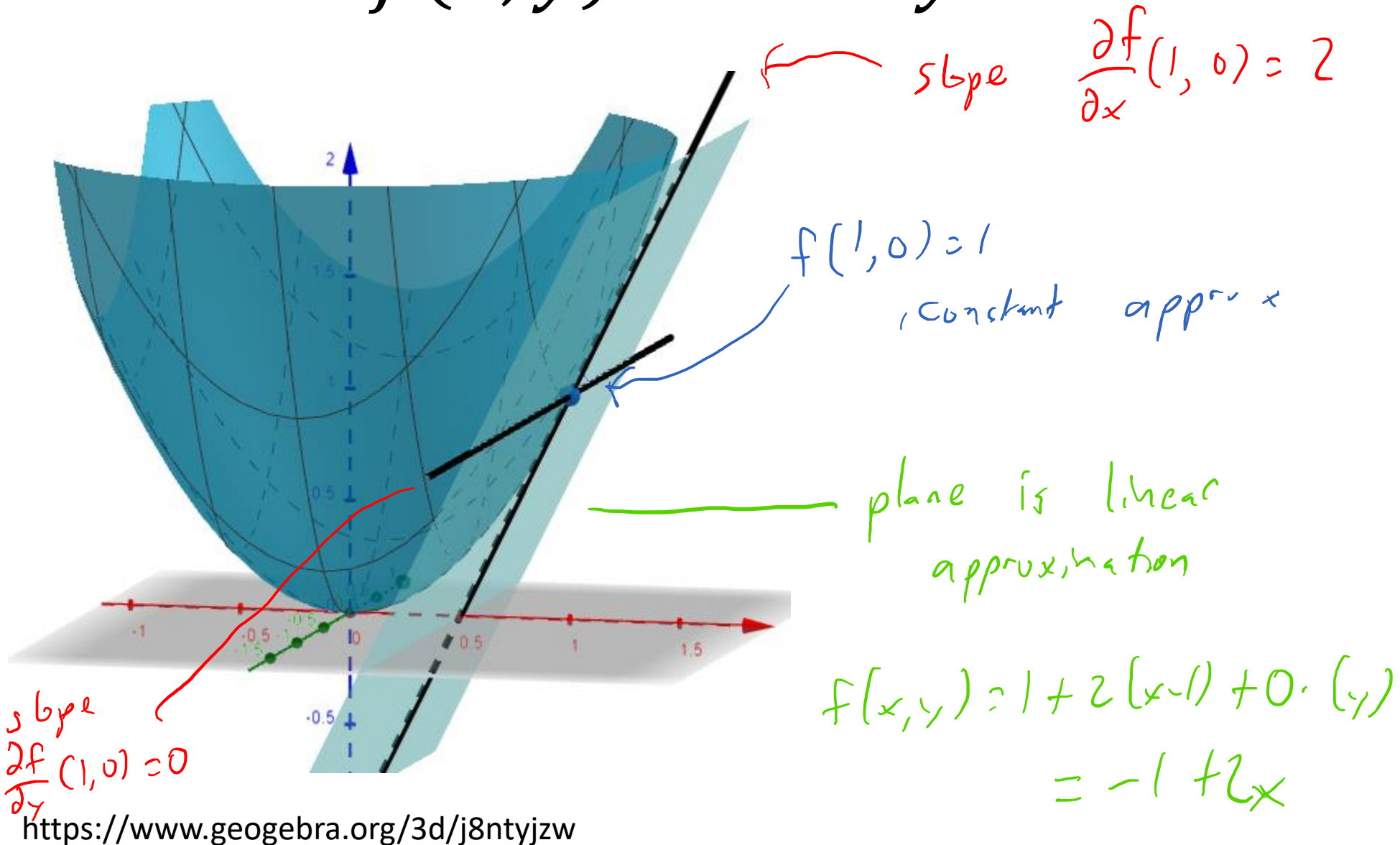
$$\underbrace{f(a)}_{\text{constant}} + \underbrace{f'(a)}_{\text{slope}}(x - a)$$

- A multivariable function  $f(x, y)$  has a linear approximation at point  $(a, b)$  of

$$\underbrace{f(a, b)}_{\text{constant}} + \underbrace{\frac{\partial f(a, b)}{\partial x}}_{\substack{\text{slope in} \\ x\text{-direction}}}(x - a) + \underbrace{\frac{\partial f(a, b)}{\partial y}}_{\substack{\text{slope in} \\ y\text{-direction}}}(y - b)$$



$$f(x, y) = x^2 + y^2$$



# Function $h: \mathbb{R}^2 \rightarrow \mathbb{R}^2$

- A multivariable function  $f(x, y)$  has a linear approximation at point  $(a, b)$  of

$$f(a, b) + \frac{\partial f(a, b)}{\partial x} (x - a) + \frac{\partial f(a, b)}{\partial y} (y - b)$$

- So,  $f(x, y) \approx f(a, b) + \begin{bmatrix} \frac{\partial f(a, b)}{\partial x} & \frac{\partial f(a, b)}{\partial y} \end{bmatrix} \begin{bmatrix} x - a \\ y - b \end{bmatrix}$

- Let  $h(x, y) = \begin{bmatrix} f(x, y) \\ g(x, y) \end{bmatrix}$ ,  $h: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  *Jacobian*

- Then

$$h(x, y) \approx \begin{bmatrix} f(a, b) \\ g(a, b) \end{bmatrix} + \overbrace{\begin{bmatrix} \frac{\partial f(a, b)}{\partial x} & \frac{\partial f(a, b)}{\partial y} \\ \frac{\partial g(a, b)}{\partial x} & \frac{\partial g(a, b)}{\partial y} \end{bmatrix}}^{\text{Jacobian}} \begin{bmatrix} x - a \\ y - b \end{bmatrix}$$

# Nonlinear phase portraits

- $$h(x, y) \approx \begin{bmatrix} f(a, b) \\ g(a, b) \end{bmatrix} + \begin{bmatrix} \frac{\partial f(a, b)}{\partial x} & \frac{\partial f(a, b)}{\partial y} \\ \frac{\partial g(a, b)}{\partial x} & \frac{\partial g(a, b)}{\partial y} \end{bmatrix} \begin{bmatrix} x - a \\ y - b \end{bmatrix}$$
- This approximation holds locally around every point, and therefore around each equilibrium.
- We can thus approximate its behavior by looking at the Jacobian matrix' eigenvalues.

