## Approximating functions

# Lecture 11c: 2023-03-30 

MAT A35 - Winter 2023 - UTSC Prof. Yun William Yu

## Approximating $\sin x$

- Recall the Taylor series

$$
\sin x=x-\frac{x^{3}}{3!}+\frac{x^{5}}{5!}-\frac{x^{7}}{7!}+\frac{x^{9}}{9!}-\cdots
$$

- Can you approximate $\sin 0.5$ by hand?
- We can often approximate a function by cutting off its Taylor series after some number of terms.


## Try it out

- What is $e^{0.5}$, approximated using the first 3 terms in its Maclaurin series?

A: 1<br>B: 1.5<br>C: 1.5625<br>D: 1.6487<br>E : None of the above

## Constant approximation of a function

- If we keep just the first term of a Taylor series, we get a constant approximation.



## Linear approximation of a function

- If we keep just the first two terms of a Taylor series, we get a linear approximation.



## Quadratic approximation of a function

- If we keep just the first three terms of a Taylor series, we get a quadratic approximation.



# Qualitative analysis using approximation 

- Often, the qualitative facts we are interested in can be captured by linear or quadratic approximation.
- Constant approximation: roughly where is the function?
- Linear approximation: is the function increasing or decreasing?
- Quadratic approximation: is the function concave up or down?


## Multivariable functions

- A function $f(x)$ has a linear approximation at $a$ of

$$
f(a)+f^{\prime}(a)(x-a)
$$

- A multivariable function $f(x, y)$ has a linear approximation at point $(a, b)$ of

$$
f(a, b)+\frac{\partial f(a, b)}{\partial x}(x-a)+\frac{\partial f(a, b)}{\partial y}(y-b)
$$

$$
f(x, y)=x^{2}+y^{2}
$$


https://www.geogebra.org/3d/j8ntyjzw

## Function $h: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$

- A multivariable function $f(x, y)$ has a linear approximation at point $(a, b)$ of

$$
f(a, b)+\frac{\partial f(a, b)}{\partial x}(x-a)+\frac{\partial f(a, b)}{\partial y}(y-b)
$$

- So, $f(x, y) \approx f(a, b)+\left[\begin{array}{ll}\frac{\partial f(a, b)}{\partial x} & \frac{\partial f(a, b)}{\partial y}\end{array}\right]\left[\begin{array}{l}x-a \\ y-b\end{array}\right]$
- Let $h(x, y)=\left[\begin{array}{l}f(x, y) \\ g(x, y)\end{array}\right], h: \mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$
- Then
$h(x, y) \approx\left[\begin{array}{l}f(a, b) \\ g(a, b)\end{array}\right]+\left[\begin{array}{ll}\frac{\partial f(a, b)}{\partial x} & \frac{\partial f(a, b)}{\partial y} \\ \frac{\partial g(a, b)}{\partial x} & \frac{\partial g(a, b)}{\partial y}\end{array}\right]\left[\begin{array}{l}x-a \\ y-b\end{array}\right]$


## Nonlinear phase portraits

- $h(x, y) \approx\left[\begin{array}{l}f(a, b) \\ g(a, b)\end{array}\right]+\left[\begin{array}{ll}\frac{\partial f(a, b)}{\partial x} & \frac{\partial f(a, b)}{\partial y} \\ \frac{\partial g(a, b)}{\partial x} & \frac{\partial g(a, b)}{\partial y}\end{array}\right]\left[\begin{array}{l}x-a \\ y-b\end{array}\right]$
- This approximation holds locally around every point, and therefore around each equilibrium.
- We can thus approximate its behavior by looking at the Jacobian matrix' eigenvalues.


