

MATB44 - 2019Prof. Yun William YuDifferential Equations IWelcome

Def. A classical ordinary differential equation (ODEs) is a functional relationship of the form

$$F(t, x, x^{(1)}, \dots, x^{(k)}) = 0$$

for the unknown function $x \in C^k(J)$, $J \subseteq \mathbb{R}$, and its derivatives $x^{(j)}(t) = \frac{d^j x(t)}{dt^j}$, $j \in \mathbb{N}_0$,

where $F \in C(U)$ with U an open subset of \mathbb{R}^{k+2} .

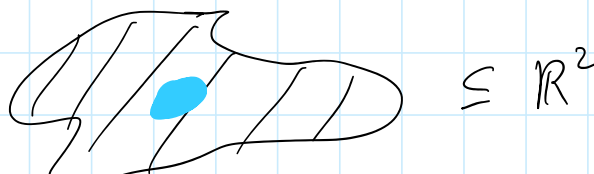
Def. A solution to an ODE is a function $\phi \in C^k(I)$, $I \subseteq J$ an interval, s.t.
 $F(t, \phi(t), \phi^{(1)}(t), \dots, \phi^{(k)}(t)) = 0$.

Set: Collection of items

Ex $\{1, \text{apple}, \star\}$, $\mathbb{N}_0 = \{0, 1, 2, 3, \dots\}$
 \mathbb{R} = all real numbers, e.g. $1, \pi, \frac{2}{7}, 5.45, 42$
 $\mathbb{R}^n = (x_1, x_2, \dots, x_n)$ - n -dim. space

Subset: A set contained in another set

$\{\star\} \subseteq \{1, \text{apple}, \star\}$ $\star \in \{1, \text{apple}, \star\}$
 positive even numbers $\subseteq \mathbb{N}_0$



$$\mathbb{R} \setminus \{0\} \cong \mathbb{R}$$

Open Subset: A set that doesn't contain boundary pts.

$$\begin{array}{c} \text{---} \text{---} \text{---} \text{---} \text{---} \\ | \quad | \quad | \quad | \quad | \\ -2 \quad -1 \quad 0 \quad 1 \quad 2 \end{array}$$

$$(-1, 1) \subset \mathbb{R}$$

does not contain -1 or 1.

More on Banach spaces and limits later.

$C^k(J)$: k -times differentiable functions on $J \subseteq \mathbb{R}$

$C^0(J)$: continuous functions

$C^1(J)$: functions with continuous 1st derivative

ex $f(x) = 0 \in C^k(\mathbb{R}) \quad \forall k \in \mathbb{N}_0 \quad (C^\infty(\mathbb{R}))$

(Leibniz notation)

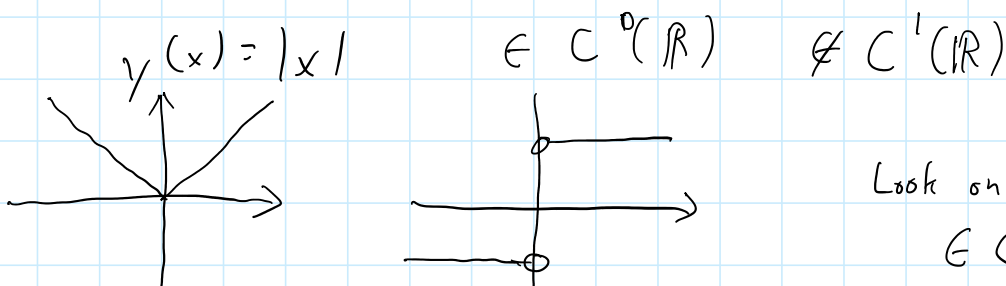
$$\frac{df(x)}{dx} = 0$$

(Lagrange notation)

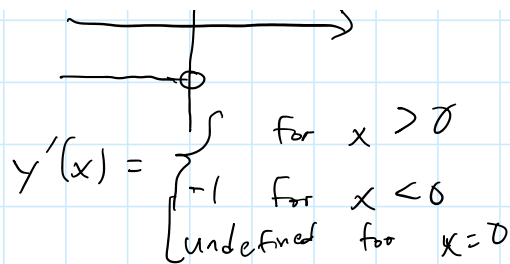
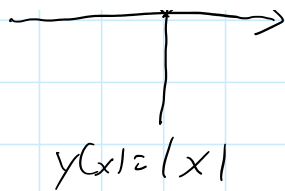
$$\left. \begin{array}{l} f(x) = x^2 + 3x - 1 \in \\ f'(x) = 2x + 3 \in \\ f''(x) = 2 \in \\ f'''(x) = 0 \in \end{array} \right\} C^\infty(\mathbb{R})$$

(Newton notation)

$$\left. \begin{array}{l} x(t) = \sin(t) \\ \dot{x}(t) = \cos(t) \\ \ddot{x}(t) = -\sin(t) \\ \ddot{\dot{x}}(t) = -\cos(t) \\ \dot{\ddot{x}}(t) = \sin(t) \end{array} \right\} \in C^\infty(\mathbb{R})$$



Look on $(0, 1) \subset \mathbb{R}$
 $\in C^\infty(0, 1)$



$\in C^\infty(0,1)$

Functional relationship = implicit function

$$F(x, y) = 0$$

ex. $x + y = 0$

$$\sin(x) - y^2 = 0$$

$$F(t, x, x') = 0$$

ex. $t^2 - x + x' = 0$

$$x - x' = 0$$

$$t + |x'| \sin(x) = 0$$

Solution: A function that can be plugged into an ODE.

Ordinary equations like $x + 3 = -1$ have solutions like $x = -4$
 ODEs like $\ddot{x} - \dot{x} + 2t - 2 = 0$ have solutions like $x = t^2$

$$x = t^2$$

$$\dot{x} = 2t$$

$$\ddot{x} = 2$$

$$2 - 2t + 2t - 2 = 0$$

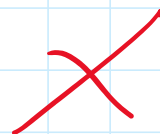
Try

$$x = 2t^2$$

$$\dot{x} = 4t$$

$$\ddot{x} = 4$$

$$4 - 4t + 2t - 2 \stackrel{?}{=} 0$$



Try

$$x = e^t t^2$$

$$\dot{x} = e^t \cdot 2t + e^t t^2$$

$$\ddot{x} = 2e^t + e^t \cdot 2t + e^t \cdot 2t + e^t t^2$$

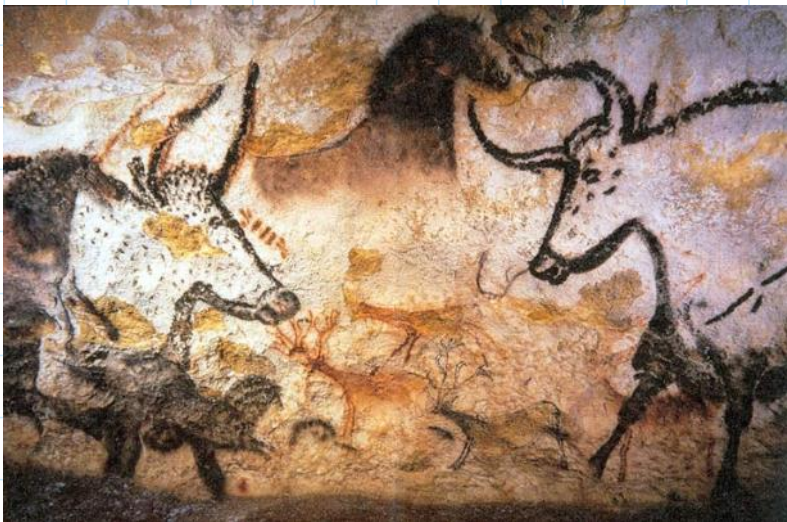
$$2e^t + 4te^t + e^t t^2 - (e^t \cdot 2t + e^t t^2) + 2t - 2 \stackrel{?}{=} 0$$



Soln. $x = t^2 + C_1 e^t + C_2$
Exercise for the audience

Radio carbon dating: Living organisms contain carbon. There are two different isotopes C^{12} and C^{14} . C^{12} is stable, but C^{14} is not. After a tree dies, C^{14} is no longer replaced & slowly decays away.

In 1940, cave paintings were discovered in Lascaux, France.



The charcoal used came from dead trees. Chemists were able to determine that 85.5% of the C^{14} present at death had decayed. When did the trees die / when were the paintings painted?

Hint: every atom of C^{14} has the same chance of decaying over a specific time period.

Half-life of C^{14} is 5730 years.

Let t = time since death of a tree
 $x(t)$ = amount of C^{14} in the tree

The decay rate is proportional to the amount.

$$\dot{x}(t) = -kx(t)$$

$$\frac{dx}{dt} = -kx$$

$$\int \frac{1}{x} \frac{dx}{dt} dt = \int -k dt$$

$$\int \frac{1}{x} dx = -kt + C_2$$

$$\ln(x) + C_1 = -kt + C_2$$

$$\ln(x) = -kt + C_3$$

$$x = e^{-kt + C_3} = e^{C_3} e^{-kt} = C_4 e^{-kt}$$

$$x(5730) = 0,5 x(0)$$

$$C e^{-5730k} = 0,5 C e^{-k \cdot 0} = 0,5 C$$

$$e^{-5730k} = 0,5$$

$$-5730k = \ln 0,5$$

$$k = 0,000121$$

$$x = C e^{-0.000121k}, \text{ where } C \text{ is the starting amount.}$$

Started with A_0 C^{14} .

End with $(1 - 0.855) A_0$ of C^{14}

$$0.145 A_0 = A_0 e^{-0.000121k}$$

$$e^{-0.000121k} = 0.145$$

$$\Rightarrow t \approx 15,959 \text{ years}$$

Classification of ODEs:

$$\text{ODE} = F(t, x, x^{(1)}, \dots, x^{(k)}) = 0$$

$t =$ independent variable (often time)

\hookrightarrow if multiple ind. var. t_1, t_2, \dots

then these are partial differential equations

$x =$ dependent variable (often space)

$\hookrightarrow x$ is a function of t i.e. $x(t)$

\hookrightarrow multiple dependent variables \Rightarrow system of ODEs

Def. The order of an ODE is the highest derivative to appear in F ,

e.g. $t + x^2 + \sin x'' = 0 \Rightarrow$ 2nd order

$\dot{x} = -kx \Rightarrow$ 1st order

$\frac{d^5 x}{dt^5} - \frac{d^2 x}{dt^2} = 0 \Rightarrow$ 5th order

$y'' - y'' + y'' - y = 0$ \Rightarrow 1st order

Note: Implicit functions are hard to work with, so we normally use a more explicit form.

$$x^{(k)} = f(t, x, x^{(1)}, \dots, x^{(k-1)})$$

With this form, we can easily write **systems of ODEs** where $x(t) : \mathbb{R} \rightarrow \mathbb{R}^n$ is a vector valued function.

(or equivalently, we have multiple dependent variables $x_1(t) : \mathbb{R} \rightarrow \mathbb{R}, x_2(t) : \mathbb{R} \rightarrow \mathbb{R}, \dots$)

$$x_1^{(k)} = f_1(t, x, x^{(1)}, \dots, x^{(k-1)})$$

$$\vdots$$

$$x_n^{(k)} = f_n(t, x, x^{(1)}, \dots, x^{(k-1)})$$

$\hookrightarrow (x_1, x_2, \dots, x_n)$

The system is linear if we can rewrite it to the form $\dot{x} = Ax + b$

The system is linear if we can rewrite it to separate out the $x_l^{(j)}$'s as follows:

$$x_i^{(k)} = g_i(t) + \sum_{l=1}^n \sum_{j=0}^{k-1} f_{i,j,l}(t) x_l^{(j)}$$

Ex. $\ddot{x} = t + \sin(t)x + t^5 \dot{x}$ - linear

$$\begin{cases} x_1'' = x_2' \\ x_2'' = t + e^t \cos(t) x_1' + x_2' - x \end{cases} \text{ - linear}$$

$$\frac{d^2x}{dt^2} = \frac{dx}{dt} - x \text{ - nonlinear}$$

$$x'' = xt \text{ - linear}$$

A linear system of ODE's is homogeneous if $g_i(t) \equiv 0$.

Ex. $\ddot{x} = t + \sin(t)x + t^5 \dot{x}$ - nonhomogeneous

$$\begin{cases} x_1'' = x_2' \\ x_2'' = t + e^t \cos(t) x_1' + x_2' - x \end{cases} \text{ nonhomogeneous}$$

$$x'' = xt \text{ - homogeneous}$$

Note that any system of ODEs can be transformed into a new first-order system by changing the dependent variables to $y = (x, x^{(1)}, \dots, x^{(k-1)})$

$$x^{(k)} = f(t, x, x^{(1)}, \dots, x^{(k-1)}) \rightarrow \begin{cases} \dot{y}_1 = y_2 \\ \dot{y}_2 = y_3 \\ \vdots \\ \dot{y}_{k-1} = y_k \end{cases}$$

$$\dot{y}_k = f(t, y) = f(t, y_1, y_2, \dots, y_k)$$

Ex. $\dot{x} + t^2 \cos(\dot{x}) = tx$

Ex. $\ddot{x} + t^2 \cos(\dot{x}) = t x$

Let $y_1 = x, \quad y_2 = \dot{x}$

$\dot{y}_1 = y_2$

$\dot{y}_2 = \ddot{x} = t x - t^2 \cos(\dot{x}) = t y_1 - t^2 \cos(y_2)$

If there is no direct dependence on t , the system is **autonomous**.

Ex $\dot{x} = -kx$ (radiocarbon dating) - **autonomous**

Often known as time-invariant systems.

Note that we can transform a nonautonomous system to an autonomous system using the same trick, by including t as a dependent variable.

Ex. $x x' + t x'' = 1$ - 2nd order

$x' + x = 0$ - 1st order, linear, homogeneous, autonomous

$x'' + t x = 0$ - 2nd order, linear, homogeneous

$x' - 3x = 5$ - 1st order, autonomous, linear

$x'' = t x' - 3t$ - 2nd order, linear

→ $x'(t) + x(t) = 0$, dependence on t is indirect so autonomous